

ARD-CNC-Kit1 Manual



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1. INTRODUCTION

Dear customer,

thank you for choosing our product.

In the following, we will show you what to observe during commissioning and use. Should you encounter any unexpected problems during use, please do not hesitate to contact us.

With this set you lay the foundation for the installation of a customized CNC milling machine. The controller board is suitable for use with the Arduino Uno or Arduino Uno compatible boards and can be operated from 12 to 36 V as needed.

With the supplied A4988 motor drivers up to 4 axes can be controlled.

The expansion board is easy to control as it is 100% GRBL compatible.

2. SAFETY INSTRUCTIONS

Since this expansion board can control potentially dangerous machines, please note the following safety instructions:

Never reach into the processing room while the machine is running.

Do not remove accumulated chips by hand.Please use a brush or compressed air.

Tools and workpieces must never be changed while the tool spindle is running

Make sure that the workpieces are sufficiently secured so that during drilling or milling, the workpiece can never be moved out of position.

Never run the machine unattended!

Always maintain sufficient safety distance to the running machine

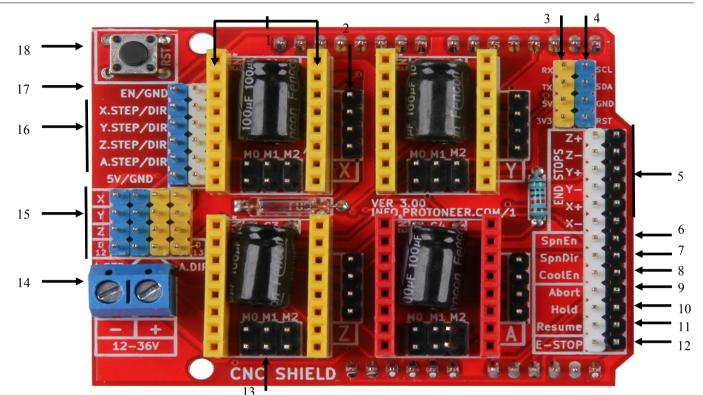
Please use the ARD-CNC-Kit1 only in dry environments.

When using components from other manufacturers, please inform yourself about their safety regulations and observe them.

We are not liable for damage caused by improper use.

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3. PINOUT



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Pin	Description
1	Motordriver
2	Stepper Motor
3	UART
4	I2C
5	End Stops
6	Enable Spindle
7	Spindle direction
8	Enable cooling
9	Abort
10	Hold
11	Resume
12	Emergency Stop
13	Jumper for Microsteps
14	Power Supply
15	Clone Axis
16	External Controll
17	Enable
18	Reset button



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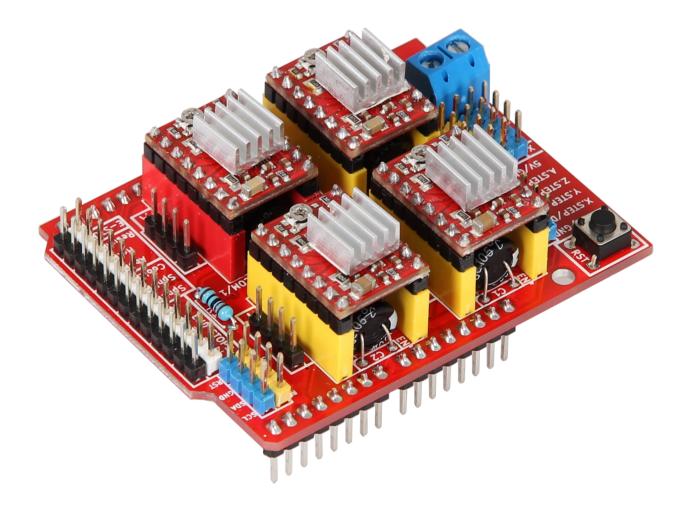
4. USAGE

The ARD-CNC-Kit1 supports the Arduino Uno and Arduino Uno compatible boards. The CNC extension board needs a additional power supply between 12 V and 36 V. IF you have connected the Motordrivers the Steppermotors and the Arduino the extensionboard is ready to go.

CAUTION!!!

Please pay attention to the correct alignment of the A4988 motor drivers, otherwise they will be damaged.

Please connect them like in the picture below.

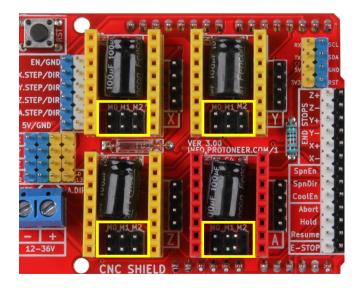


5. MICROSTEPPING

Jumper Positioning for Microsteps

M0	M1	M2	Microsteps
-	-	-	1 Steps
+	-	-	1/2 Steps
-	+	-	1/4 Steps
+	+	-	1/8 Steps
+	+	+	1/16 Steps

+ = Jumper set - = Jumper not set



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6. CODE EXAMPLE

On the following two sites you can see an easy example code for testing your CNC Kit.

CAUTION!!!

No End Stop detection. Motors won't stop automatically.

```
#define EN 8
              /* Enable pin for all stepper outputs */
#define X DIR 5 /* Direction-Pin for X-axis */
#define X STEP 2 /* Step-Pin for X-axis */
#define Y DIR 6 /* Direction-Pin for Y-axis*/
#define Y STEP 3 /* Step-Pin for Y-axis */
#define Z DIR 7 /* Direction-Pin for Z-axis */
#define Z STEP 4 /* Step-Pin for Z-axis */
#define A DIR 13 /* Direction-Pin for A-axis*/
#define A STEP 12 /* Step-Pin for A-axis */
int Count = 0; /* Counter to count number of steps made */
boolean Direction = LOW; /* Rotational direction of stepper motors*/
void setup()
ł
 Serial.begin(9600);
 /* Configure the stepper drive pins as outputs */
 pinMode(EN, OUTPUT);
 pinMode(X DIR, OUTPUT);
 pinMode(X STEP, OUTPUT);
 pinMode(Y DIR, OUTPUT);
 pinMode(Y STEP, OUTPUT);
 pinMode(Z DIR, OUTPUT);
 pinMode(Z STEP, OUTPUT);
 pinMode(A DIR, OUTPUT);
 pinMode(A_STEP, OUTPUT);
 digitalWrite(EN, LOW); //Low to enable
}
```

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6. CODE EXAMPLE CONTINUED

void loop()
{
/* Count one step */
Count++;
/* If reached 500 steps then change the stepper direction and resset the counter*/
if (Count >= 500)
Direction = !Direction;
digitalWrite(X_DIR, Direction); // Low = CW
digitalWrite(Y DIR, Direction); // Low = CW
digitalWrite(Z DIR, Direction); // Low = CW
digitalWrite(A DIR, Direction); // Low = CW
Count = 0;
}
/* Step the X, Y, Z, und A Motoren */
digitalWrite(X STEP, HIGH);
delay(1);
digitalWrite(Y STEP, HIGH);
delay(1);
digitalWrite(Z STEP, HIGH);
delay(1);
digitalWrite(A STEP, HIGH);
delay(1);
digitalWrite(X STEP, LOW);
delay(1);
digitalWrite(Y STEP, LOW);
delay(1);
digitalWrite(Z STEP, LOW);
delay(1);
digitalWrite(A_STEP, LOW);
delay(1);
}



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7. SUPPORT

We also support you after your purchase. If there are any questions left or if you encounter any prob lems please feel free to contact us by mail, phone or via our ticket support system on our website.

E-Mail:	service@joy-it.net
Ticket-System:	http://support.joy-it.net
Telefon:	+49 (0)2845 98469 – 66 (10- 17 Uhr)

Visit our website for more informations:

www.joy-it.net