



General Description

The DE-ACCM6G is an off the shelf 2 axis 6g accelerometer solution with analog outputs. It features integrated op amp buffers for direct connection to a microcontroller's analog inputs, or for driving heavier loads.

Additional circuitry ensures that the product won't be damaged by reversed power connections, or voltages above the recommended ratings.

The DE-ACCM6G is designed to fit the DIP-14 form factor, making it suitable for breadboarding, perfboarding, and insertion into standard chip sockets.

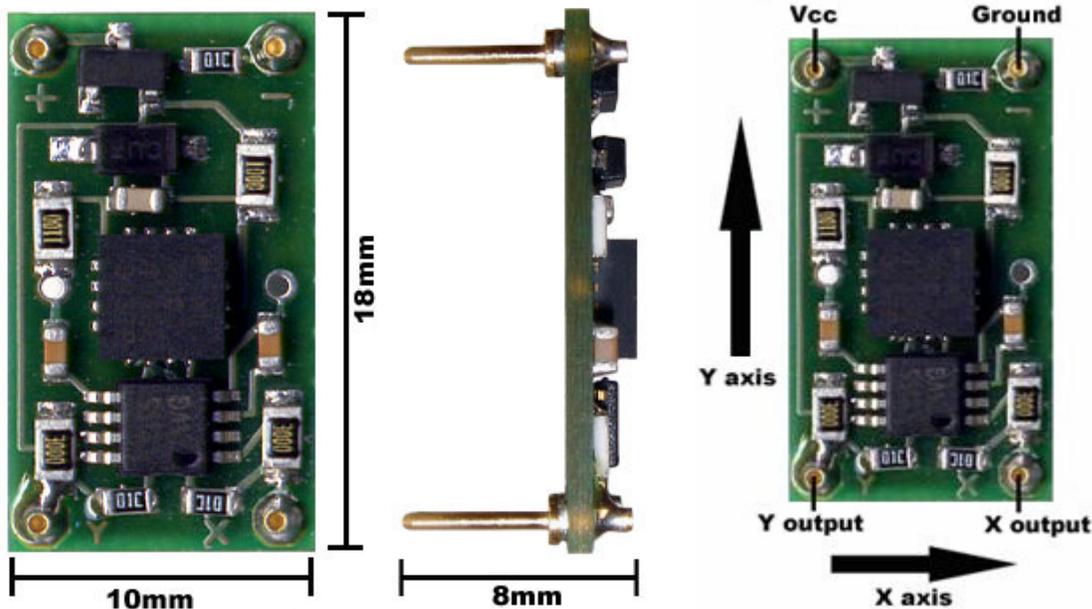
It is based on the ST MicroElectronics LIS244ALH for superior sensitivity and lower cost.

Features

- Dual axis $\pm 6g$ sense range
- 222mV/g sensitivity
- 500Hz bandwidth
- Operating voltage 4 to 15V
- Onboard 3.3V voltage regulator
- Reverse voltage protection
- Output short protection
- Standard DIP-14 form factor
- Integrated power supply decoupling
- Draws under 2mA
- Shiny gold pins to distract the enemy!

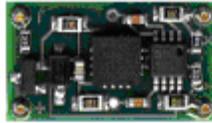
Applications

- Motion, tilt and slope measurement
- Shock sensing
- Vehicle acceleration logging



Measuring acceleration and tilt

VCC = 3.3V



Xout = 1.44V
Yout = 1.66V



Xout = 1.66V
Yout = 1.66V

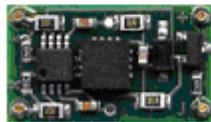


Xout = 1.66V
Yout = 1.88V



Xout = 1.66V
Yout = 1.44V

Gravity's
accelerative
force of 1g



Xout = 1.88V
Yout = 1.66V



The voltage outputs on the DE-ACCM6G correspond to acceleration being experienced in the X and Y directions. The output is ratiometric, so the output sensitivity (in mV/g) will depend on the supply voltage. Sensitivity is typically 222mV/g. Zero acceleration (0g) will result in an output of $V_{cc}/2$ regardless of the voltage supplied to the unit.

Due to manufacturing variances when ST Microelectronics makes their accelerometer chips, these values aren't always set in stone. They can vary by up to 4% in extreme cases, including the 0g bias point. For projects that require a very high degree of accuracy, we recommend that you incorporate measured calibrations into your hardware/software.

Voltage to acceleration example:

"The X output reads 2.96V. What acceleration does this correspond to?"

The 0g point is approximately $V_{cc} / 2 = 3.33 / 2 = 1.66V$

$2.96V - 1.66V = +1.20V$ with respect to the 0g point

Sensitivity is 222mV/g, $1.2 / 0.312 = 5.41g$

Therefore the acceleration in the X direction is 5.41g

Acceleration to voltage example:

"What voltage will correspond to an acceleration of -0.5g?"

The 0g point is approximately 1.66V

Sensitivity is 222mV/g, $-0.5 * 0.222 = -0.111V$ with respect to the 0g point.

$1.66V - 0.111V = 1.55V$

Therefore you can expect a voltage of approximately 1.55V when experiencing an acceleration of -0.5g.

Voltage to tilt example:

"With the accelerometer oriented flat and parallel to ground in my robot, Yout is 1.66V. When my robot goes uphill, Yout increases to 1.765V. What is the slope of the hill?"

$1.765V - 1.66 = +0.105V$ with respect to the 0g point.

With a sensitivity of 222mV/g, $0.105 / 0.222 = 0.471g$

$\sin^{-1}(0.471) = 28.1^\circ$

The slope of the hill is 28.1° in the Y axis

Tilt to voltage example:

"I am making an antitheft device that will sound an alarm if it is tilted more than 10° with respect to ground in any direction. I have measured the 0g bias point to be 1.663V, and I want to know what voltage to trigger the alarm at."

$\sin(10^\circ) = 0.1736$ so acceleration with a tilt of 10° will be 0.1736g

$0.1736g * 0.222V/g = 0.0385V$ with respect to the 0g point

$1.663 + 0.0385 = 1.7015V$

$1.663 - 0.0385 = 1.6245V$

Sound the alarm when the voltage reaches more than 1.7015V or less than 1.6245V.

Performance features

Output buffers

A bare accelerometer chip has an output impedance of $32\text{k}\Omega$, which is unsuitable for obtaining reliable measurements when connected to an analog to digital converter. On the DE-ACCM6G, a dual rail to rail operational amplifier buffers the outputs from the LIS244ALH, greatly reducing output impedance.

→ Buffer loading characteristics

For the purposes of this section, “max load” is defined as the resistive load that will cause a 2mV drop in the output voltage at 0g. If your application does not require this level of accuracy, the DE-ACCM6G can supply even more current at the cost of a larger drop in output voltage.

Max load is 0.83mA, or a resistance of $3\text{k}\Omega$

Supply filtering

A pair of resistors and a 0.1uF ceramic bypass capacitor on the DE-ACCM6G provide excellent power supply decoupling. No external capacitors are necessary between Vcc and GND.

Output filtering and noise

A pair of 10nF capacitors limit the noise figure of the DE-ACCM6G, without overly sacrificing bandwidth. RMS noise is typically 7.1mg, and output bandwidth is 500Hz - making it suitable for high frequency sampling of acceleration.

Protection features

Reverse voltage

Even the best engineers sometimes get their wires crossed. In the event that you mix up VCC and GND, a P channel MOSFET will prevent current from flowing – protecting the DE-ACCM6G from damage. This protection is only designed to work with DC voltages. Do not apply AC voltages to the power pins.

Improper insertion

A resistor network ensures that the DE-ACCM6G will not be permanently damaged if you insert it backwards (i.e. apply power to the output pins). The product will not function properly while it is used backwards. Do not leave the DE-ACCM6G inserted backwards for more than 5 minutes at a time.

Output shorting

The operational amplifier driving the DE-ACCM6G's outputs is capable of handling a direct short from the X and Y outputs to ground for as long as you want.