

Read this document carefully before using this device. The guarantee will be expired by device demages if you don't attend to the directions in the user manual. Also we don't accept any compensations for personal injury, material damage or capital disadvantages.

ENDA ET4420 PID TEMPERATURE CONTROLLER

Thank you for choosing **ENDA ET4420 PID** temperature controller.

- * 48 x 48mm sized.
- * Selectable dual setpoint.
- * Selectable thermocouple types.
- * Automatic calculation of PID parameters. (SELFTUNE).



Selftune for automatic PID calculation or manually enter PID parameters if known.

- * Three different specifications can be assigned to digital input.
- * Three different specifications can be assigned to F function key.
- * Soft-Start feature.
- * Selectable SSR control output.
- * C/A2 Relay output programmable as secondary alarm or control output.
- * A1 Relay output programmable as primary alarm or PID cooling output.
- * Selectable heating/cooling control.
- * Zero point input shift.
- * In the case of sensor failure, manually, periodical or auto-periodical control can be selected.
- * RS485 ModBus protocol communication feature.(optional)
- * CE marked according to European Norms.





TECHNICAL SPECIFICATIONS

Input Type		Tempera	ture Range	Accuracy	
		°C	°F		
PT100 Resistance thermometer	er EN 60751	-199.9600.0 °C	-199.9999.9 °F	± 0,2% (of full scale) ± 1 hane	
PT100 Resistance thermometer	er EN 60751	-200600 °C	-3281112 °F	± 0,2% (of full scale) ± 1 hane	
J (Fe-CuNi) Thermocouple	EN 60584	-30.0600.0°C	-22.0999.9 °F	± 0,5% (of full scale) ± 1 hane	
J (Fe-CuNi) Thermocouple	EN 60584	-30600°C	-221112 °F	± 0,5% (of full scale) ± 1 hane	
K (NiCr-Ni) Thermocouple	EN 60584	-30.0999.9°C	-22.0999.9 °F	± 0,5% (of full scale) ± 1 hane	
K (NiCr-Ni) Thermocouple	EN 60584	-301300°C	-222372 °F	± 0,5% (of full scale) ± 1 hane	
L (Fe-CuNi) Thermocouple	DIN 43710	-30.0600.0°C	-22.0999.9 °F	± 0,5% (of full scale) ± 1 hane	
L (Fe-CuNi) Thermocouple	DIN 43710	-30600°C	-221112 °F	± 0,5% (of full scale) ± 1 hane	
T (Cu-CuNi) Thermocouple	EN 60584	-30.0400.0°C	-22.0752.0 °F	± 0,5% (of full scale) ± 1 hane	
T (Cu-CuNi) Thermocouple	EN 60584	-30400°C	-22752 °F	± 0,5% (of full scale) ± 1 hane	
S (Pt10Rh-Pt) Thermocouple	EN 60584	-401700°C	-403092 °F	± 0,5% (of full scale) ± 1 hane	
R (Pt13Rh-Pt) Thermocouple	EN 60584	-401700°C	-403092 °F	± 0,5% (of full scale) ± 1 hane	

ENVIRONMENTAL CONDITIONS					
Ambient/storage temperature	0 +50°C/-25 +70°C (with no icing)				
Max. Relative humidity	Relative humidity 80% for temperatures up to 31°C decreasing linearly to 50% relative humidity at 40°C.				
Rated pollution degree	According to EN 60529 Front panel: Ip65, Rear panel: Ip20				
Height	Max. 2000m				



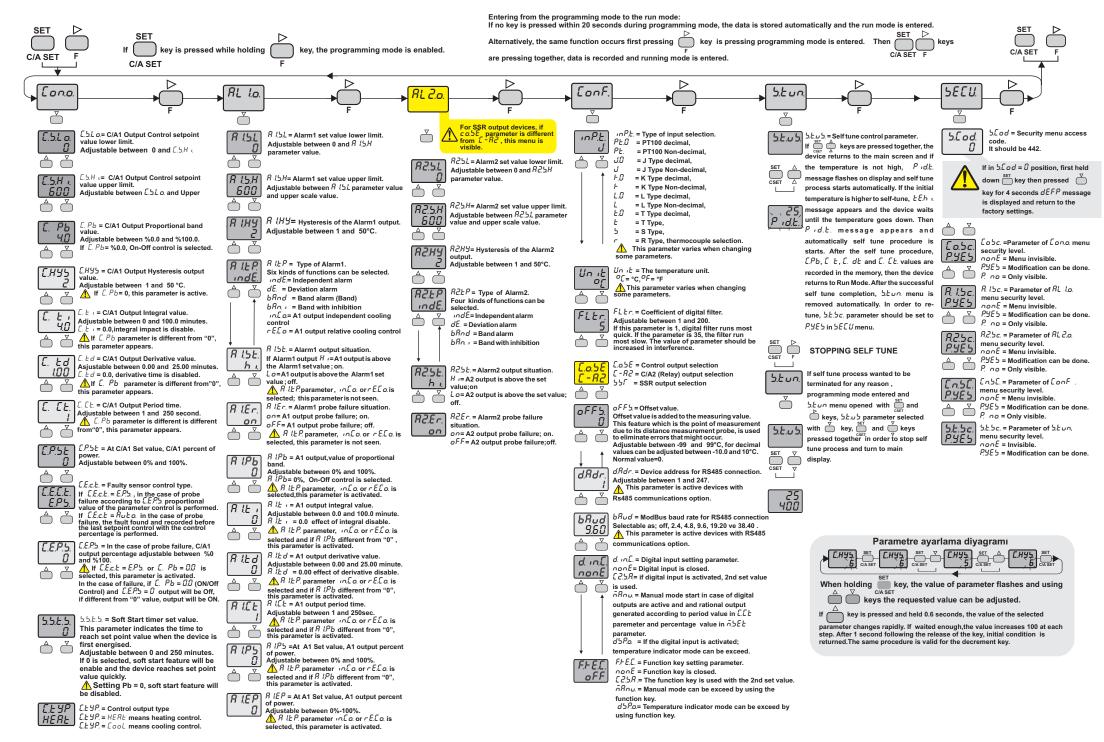
Do not use the device in locations subject to corrosive and flammable gases.

Do not use the device in locations subject to corrosive and flammable gases.				
RISTICS				
110V AC +%10 -%20, 230V AC +%10 -%20, 50/60Hz or 24V AC %10, ±50/60Hz				
Max. 5VA				
Power connector: 2.5mm² screw-terminal, Signal connector: 1,5mm² screw-terminal conenction.				
Max. 100ohm				
EEPROM (minimum 10 years)				
EN 61326-1: 2012				
EN 61010-1: 2010 (Pollution degree 2, overvoltage category II)				
Relay: 250V AC, 2A (for resistive load), Selectable as NO+NC Control or Alarm2 output.				
Relay: 250V AC, 2A (for resistive load), NO (Selectable as Alarm1 and Cooling Control output).				
Max 20mA 24Volt				
Mechanical 30.000.000; Electrical 100.000 operation. 250V AC, 2A (resistive load).				
Single set-point and alarm control				
On-Off / P, PI, PD, PID (selectable)				
12 bit				
100ms				
Adjustable between 0% and 100%. If Pb=0.0%, On-Off control is selected.				
Adjustable between 1 and 125 seconds				
Adjustable between 1 and 50°C/F				
The ratio of power at a set point can be adjusted between 0% and 100%				
Suitable for flush-panel mounting according to DIN 43 700.				
W48xH48xD87mm				
Approx. 250g (after packing)				
Self extinguishing plastics.				



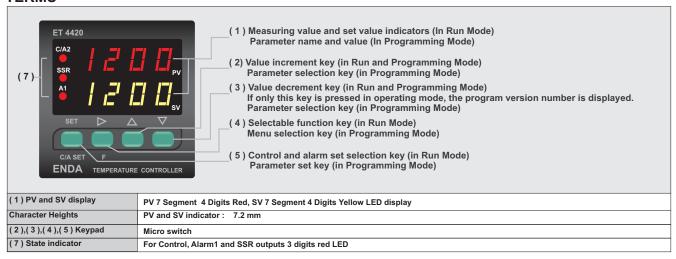


While cleaning the device, solvents (thinner, benzine, acid etc.) or corrosive materials must not be used.

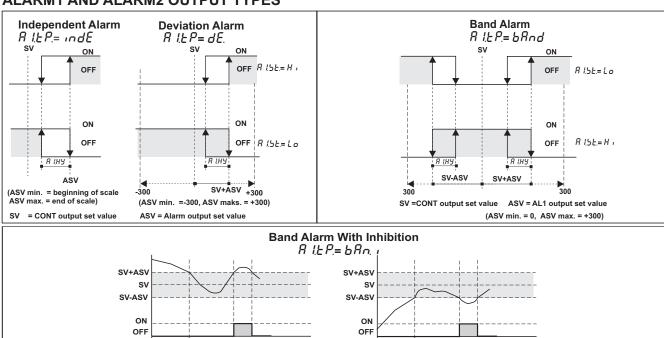


2/7 ET4420-E-01-150611

TERMS



ALARM1 AND ALARM2 OUTPUT TYPES



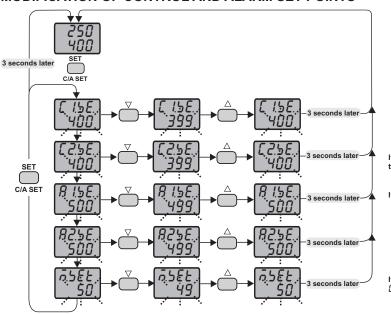
SV = Set point of CONT output ASV = Set point of AL1 output (ASV min. = 0, ASV max. = 300)

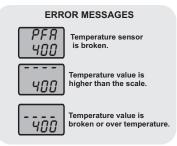
Beginning

MODIFICATION OF CONTROL AND ALARM SET POINTS

Beginning

Band alarm is possible





If one of the d, i.e., or F.F.E.c. parameters are set to the $\mathcal E$ 2.5. $\mathcal R$ value, this parameter is seen.

Band alarm is possible

If the $\mathcal{L}.o.5\mathcal{E}$, parameter is set to SSR out, this parameter is seen.

If one of the d, inc, or F, F, E, e, parameters are set to the $\tilde{n}Rnu$, value and if E. Pb is different from 0, this parameter is seen.





DIMENSIONS:

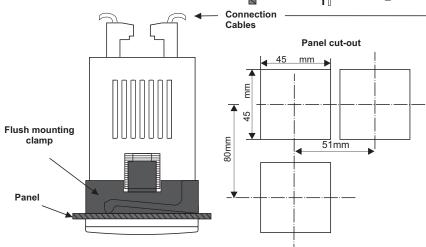
58mm

Depth 87mm **- 2** 1∥

For removing the device from the panel:

- While pressing both side of the device in direction 1, push it in direction 2.

- 1) While panel mounting, additional distance required for connection cables should be considered.
- 2) Panel thickness should be maximum 9mm.
- 3) If there is no 100mm free space at back side of the device, it would be difficult to remove it from the panel.

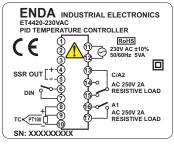


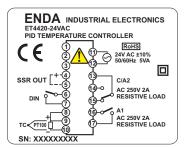


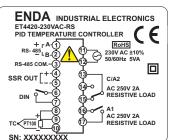
ENDA ET4420 is intended for installation in control panels. Make sure that the device is used only for intended purpose.

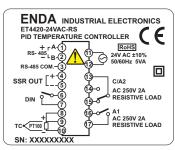
The shielding must be grounded on the instrument side. During an installation all of the cables that are connected to the device must be free of energy. Device must be protected against inadmissible humidity, vibrations, severe soiling and make sure that the operation temperature is not exceeded. All input and output lines that are not connected to the supply network must be laid out as shielded and twisted cables. These cables should not be close to the power cables or components. The installation and electrical connections must be carried on by a qualified staff and must be according to the relevant locally applicable regulations.

CONNECTION DIAGRAM











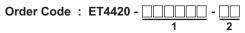
Logic output of the instrument is not electrically insulated from the internal circuits. Therefore, when using a grounding thermocouple, do not connect the logic output terminals to the ground.

Note: 1) Mains supply cords shall meet the requirements of IÉC 60227 or IÉC 60245.

2) In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument and it should be easily accessible by the operator.



Equipment is protected throughout by DOUBLE INSULATION.

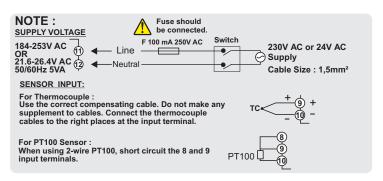


1- Supply Voltage 110VAC...110V AC 230VAC...230V AC 24VAC.....24V AC

2- Modbus Option

RS......RS-485 Modbus Communication

None...RS-485 ModBus Communication not supported.







ENDA ET4420 PID TEMPERATURE CONTROLLER MODBUS ADDRESS MAP

1.1 Memory Map for Holding Registers

	Parameter Number	Holding Register Addresses Desimal (Hex)	Data Type	Data Content	Read / Write Permission	Factory Defauls
	Н0	0000d (0000h)	Word	Control output, temperature setpoint value	Read / Write	400
ဟ	H1	0001d (0001h)	Word	Control output, 2nd temperature setpoint value	Read / Write	400
Control Output Parameters	H2	0002d (0002h)	Word	Control output, minimum setpoint value	Read / Write	0
ame	Н3	0003d (0003h)	Word	Control output, maximum setpoint value	Read / Write	600
Jar	H4	0004d (0004h)	Word	Control output, proportional band setpoint value (Adjustable between %0.0 and %100.0)	Read / Write	4
T T	H5	0005d (0005h)	Word	Control output, hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
l tb	H6	0006d (0006h)	Word	Control output, integral time (Adjustable between 0.1 and 100.0 minute)	Read / Write	40
0	H7	0007d (0007h)	Word	Control output, derivative time (Adjustable between 0.01 and 10.00 minute)	Read / Write	100
ıtro	H8	0008d (0008h)	Word	Control output, time period setpoint value (Adjustable between 1 and 125 second)	Read / Write	20
S	H9	0009d (0009h)	Word	Control output, set value power ratio (Adjustable between %0 and %100)	Read / Write	0
	H10	0010d (000Ah)	Word	Control output, set value power ratio in case of sensor failure (Adjustable between %0 and %100)	Read / Write	0
	H11	0011d (000Bh)	Word	Control output, soft start value	Read / Write	0
	H12	0012d (000Ch)	Word	Alarm1 output temperature setpoint value	Read / Write	500
	H13	0013d (000Dh)	Word	Alarm1 output minimum setpoint value limit	Read / Write	0
ဟု	H14	0014d (000Eh)	Word	Alarm1 output maximum setpoint value limit	Read / Write	600
Parameters	H15	0015d (000Fh)		Alarm1 output proportional band set value (Adjustable between %0.0 and %100.0)	Read / Write	0
E E	H16	0016d (0010h)	Word	Alarm1 output hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
ara	H17	0017d (0011h)	Word	Alarm1 output, integral time (Adjustable between 0.1 and 100.0 minute)	Read / Write	0
		0018d (0012h)	Word	Alarm1 output, derivative time (Adjustable between 0.01 and 10.00 minute)	Read / Write	0
Output	H19	0019d (0012h)	Word	Alarm1 output, time period setpoint value (Adjustable between 1 and 125 second)	Read / Write	20
o	H20	0020d (0014h)	Word	Alarm1 output, set value power ratio (Adjustable between %0 and %100)	Read / Write	0
A	H21	, ,	Word	, , , , , , , , , , , , , , , , , , ,		0
	H22	0021d (0015h)		Alarm1 output, set value power ratio in case of sensor failure (Adjustable between %0 and %100) Alarm1 output type selection (Values can be given from 0 to 4) (0 = Independent alarm,	Read / Write	0
	ПZZ	0022d (0016h)	Word	1 = Deviation alarm, 2 = Band alarm, 3 = Active alarm after in band time, 4 = Alarm1 output, cooling control selection)	Read / Write	0
ers	H23	0023d (0017h)	Word	Alarm2 output, temperature setpoint value	Read / Write	500
ame	H24	0024d (0018h)	Word	Alarm2 output minimum setpoint value limit	Read / Write	0
Par	H25	0025d (0019h)	Word	Alarm2 output maximum setpoint value limit	Read / Write	600
Output Parameters	H26	0026d (001Ah)		Alarm2 output, hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
A2 0	H27	0027d (001Bh)	Word	Alarm2 output type selection (Values can be given from 0 to 3) (0 = Independent alarm, 1 = Deviation alarm, 2 = Band alarm, 3 = Active alarm after in band time)	Read / Write	0
	H28	0028d (001Ch)	Word	Input selection number (0 = PT100 Decimal, 1 = Pt100 Non-decimal, 2 = J Decimal, 3 = J Non-decimal, 4 = K Decimal, 5 = K Non-decimal, 6 = L Decimal, 7 = L Non-decimal, 8 = T Decimal, 9 = T Non-decimal, 10= S Non-decimal, 11 = R Non-decimal.	Read / Write	5
SIC	H29	0029d (001Dh)	Word	ModBus device address (Adjustable between 1 and 247)	Read / Write	1
Parameters	H30	0030d (001Eh)	Word	Modbus communication speed (Baudrate) (0 = Modbus cancel, 1 = 2400 bps, 2 = 4800 bps, 3 = 9600 bps, 4 = 19200 bps, 5 = 38400 bps)	Read / Write	3
ara	H31	0031d (001Fh)	Word	Digital filter coefficient (Adjustable between 1 and 200, 1 = filter is disable)	Read / Write	10
	H32	0032d (0020h)	Word	Control output, selection value (0 = C/A2 Control output selection, 1 = SSR Output)	Read / Write	0
tiol	H33	0033d (0021h)	Word	Reserved	Read / Write	XX
ura	H34	0034d (0022h)	Word	Reserved	Read / Write	XX
figi	H35	0035d (0023h)	Word	Offset value	Read / Write	0
Configuration	H36	0036d (0024h)	Word	Function control parameter. (23040d (5A00h) self tune stops when this value is entered) (23041d (5A01h) self tune starts when this value is entered) (23042d (5A02h) returns to factory defaults when this value is entered)	Read / Write	0
	H37	0037d (0025h)	Word	Reserved	Read / Write	XX
	H38	0038d (0026h)	Word	Reserved	Read / Write	XX
	H39	0039d (0027h)	Word	Manual control output percentage (Adjustable between %0 and %100)	Read / Write	50





1.1 Memory Map for Holding Registers (continue)

	Parameter Number	Holding R Addres Desimal	sses	Data Type	Data Content	Read / Write Permission	Factory Defauls
	H40	0040d ((0028h)	Word	Digital input control parameter (0 = Digital input off, 1 = 2nd set value is selected with digital input, 2 = Manual mode is entered via digital input, 3 = Digital input is passed to display mode	Read / Write	0
	H41	0041d ((0029h)	Word	Function key control parameter (0 = Function key off, 1 = 2nd Set value is selected with function key, 2 = Manual mode is entered via function key, 3 = With the function key display mode is entered)	Read / Write	0
SLS	H42	0042d ((002Ah)	Word	Reserved	Read / Write	XX
ete	H43	0043d ((002Bh)	Word	Reserved	Read / Write	XX
aram	H44	0044d ((002Ch)	Word	Reserved	Read / Write	XX
ara	H45	0045d ((002Dh)	Word	Reserved	Read / Write	XX
n P	H46	0046d ((002Eh)	Word	Reserved	Read / Write	XX
<u>.</u>	H47	0047d ((002Fh)	Word	Reserved	Read / Write	XX
Configuratio	H48	0048d ((0030h)	Word	Control output menu, security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
nfig	H49	0049d ((0031h)	Word	Alarm1 output menu security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
ပိ	H50	0050d ((0032h)	Word	Alarm2 output menu, security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
	H51	0051d ((0033h)	Word	Configuration menu, security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
	H52	0052d ((0034h)	Word	Self tune menu, security parameter (0 = Menu invisible, 1 = Self tune can be done)	Read / Write	1

1.2 Memory Map for Coils

Parameter Number	Coil Addresses	Data Type	Data Content	Read / Write Permission	Factory Defauls
C0	(0000)h	Bit	Alarm2 Status (0 = Active Low ,1 = Active High)	Read / Write	1
C1	(0001)h	Bit	Alarm2 output position in case of Prob failure (0 = Off , 1 = On)	Read / Write	0
C2	(0002)h	Bit	Alarm1 Status (0 = Active Low ,1 = Active High)	Read / Write	1
C3	(0003)h	Bit	Alarm1 output position in case of Prob failure (0 = Off , 1 = On)	Read / Write	0
C4	(0004)h	Bit	Control output configuration (0 = Heat; 1 = Cool)	Read / Write	0
C5	(0005)h	Bit	Temperature unit (0 = °C; 1 = °F)	Read / Write	0
C6	(0006)h	Bit	Control outputs active (0 = Control outputs active, 1 = Only display mode)	Read / Write	0
C 7	(0007)h	Bit	Controlling according to 2nd temperature setpoint (If C7 = 0 is H0, if C7 = 1 is H1)	Read / Write	0
C8	(0008)h	Bit	Auto/Manual selection (0 = Automatic Run Mode, 1 = Manual Run Mode. In this mode, output generated according to H39 parameter.)	Read / Write	0
C9	(0009)h	Bit	Control format in case of probe failure (0 = H10 proportional control according to percentage value, 1 = Error found before the setpoint control is done with the value of the proportional control	Read / Write	0

1.3 Memory Map for Input Registers

Parameter Number	Input Register Addresses Desimal (Hex)	Data Type	Data Content	Read / Write Permission
10	0000d (0000h)	Word	Measured temperature	Read Only
11	0001d (0001h)	Word	Percentage of analog output	Read Only
12	0002d (0002h)	Word	Measurement error codes 0 = No error, 1 = Sensor disconnected or broken, 2 = Lower scale error, 3 = Upper scale error, 4 = PT100 short circuit or temperature too low, 5 = Wrong input selection	Read Only
13	0003d (0003h)	Word	Self tune condition codes 0 = No error, 1 = Initial temperature is higher than 60% setpoint value, 2 = Calculating PID parameters, 3 = Calculating power set parameters	Read Only
14	0004d (0004h)	Word	Current (active) temperature setpoint.	Read Only
15	0005d (0005h)	Word	Reserved	Read Only
16	0006d (0006h)	Word	Current (active) decimal point value (0 = No decimal point, 1 = 0.0 Decimal point is tenths	Read Only

.4 Memory Map for Software Revision Input Registers							
Software Revision 61472d (F020h) Word	Software name and update is read in ASCII format and as 14 word. Sample : ET4420-01 03 Dec 2013.	Read Only					
	Memory Formats : Word Word Word Word Word Word Word Word						





1.5 Memory Map for Discrete input

Parametre Numarası	Discrete Input Addresses	Data Type		Read / Write Permission
D0	(0000)h	Bit	C/A2 Control output status (0 = OFF ,1 = ON)	Read Only
D1	(0001)h	Bit	A1 Output status (0 = OFF , 1 = ON)	Read Only
D2	(0002)h	Bit	SSR Output status (0 = OFF ,1 = ON)	Read Only
D3	(0003)h	Bit	Digital input status (0 = OFF ,1 = ON)	Read Only

2. MODBUS ERROR MESSAGES

Modbus protocol has two types error, communication error and operating error. Reason of the communication error is data corruption in transmission. Parity and CRC control should be done to prevent communication error. Receiver side checks parity and CRC of the data. If they are wrong, the message will be ignored. If format of the data is true but function doesn't perform for any reason, operating error occurs. Slave realizes error and sends error message. Most significant bit of function is changed '1' to indicate error in error message by slave. Error code is sent in data section. Master realizes error type via this message.

ModBus Error Codes

Error Code	Name	Meaning
01	ILLEGAL FUNCTION	The function code received in the query is not an allowable action for the slave. If a Poll Program Complete command was issued, this code indicates that no program function preceded it.
02	ILLEGAL DATA ADDRESS	The data address received in the query is not an allowable address for the slave.
03	ILLEGAL DATA VALUE	A value contained in the query data field is not an allowable value for the slave.

Message example;

Structure of command message (Byte Format)

Device Addres	(0A)h	
Function Code	(01)h	
Beginning address	MSB	(04)h
of coils.	LSB	(A1)h
Number of coils (N)	MSB	(00)h
ramper or come (iv)	LSB	(01)h
CRC DATA	LSB	(AC)h
CRC DATA	MSB	(63)h

Structure of response message (Byte Format)

Function Code (81)h Error Code (02)h	Device Addres	(0A)h	
Error Code (02)h	Function Code	(81)h	
	Error Code	(02)h	
LSB (B0)h	CDC DATA	(B0)h	
CRC DATA MSB (53)h	CRC DATA	MSB	(53)h

As you see in command message, coil information of (4A1)h = 1185 is required but there isn't any coil with 1185 address. Therefore error code with number (02) (Illegal Data Address) sends.



